Laboratory 5

(Due date: **005**: March 29th, **006**: March 30th)

OBJECTIVES

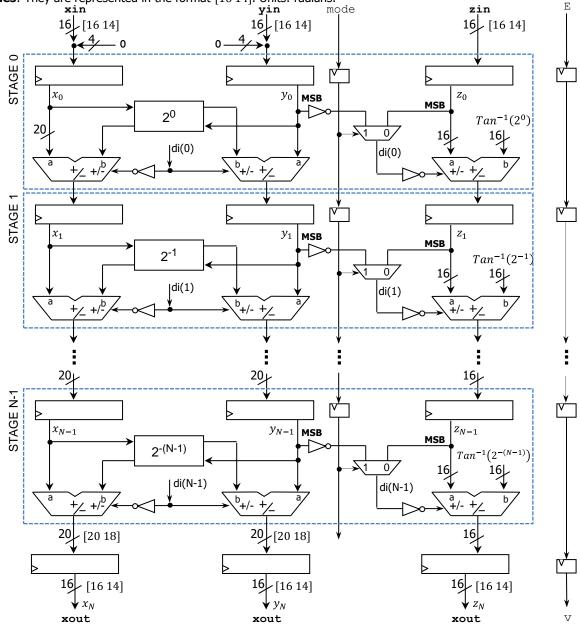
- ✓ Design a pipelined circuitry for trigonometric circuit (CORDIC) in Fixed-point Arithmetic.
- ✓ Test the CORDIC circuit using real data represented in Fixed-Point Arithmetic.
- ✓ Learn how to read input and output text files for Simulation.

VHDL CODING

✓ Refer to the <u>Tutorial: VHDL for FPGAs</u> for parametric code for: adder/subtractor and register.

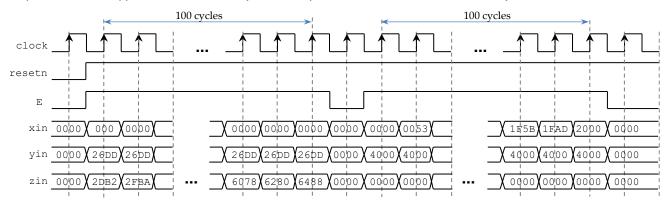
FIRST ACTIVITY: PIPELINED FX CIRCULAR CORDIC: DESIGN AND SIMULATION (100/100) Design Problem

- Pipelined Circular CORDIC architecture (basic range of convergence) with N iterations (i = 0,1,2,...,N-1). It is shown in the figure below. $mode = `0' \rightarrow \text{Rotation Mode}$. $mode = `1' \rightarrow \text{Vectoring Mode}$.
- Write the VHDL code for the circuit. Use parametric VHDL code with N as the only parameter. N = 4 to 16.
- Tip: Implement a stage i as a parametric component. Then on the top file, just instantiate N of those components.
- **Angles**: They are represented in the format [16 14]. Units: radians.



SIMULATION

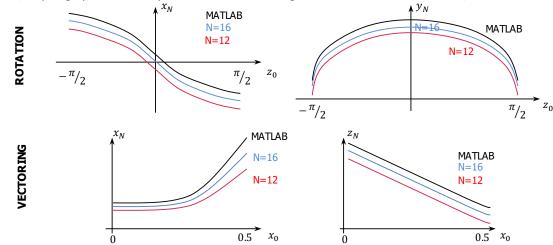
- Create a testbench that reads input values (x_0, y_0, z_0) from input text files and writes output values (x_N, y_N, z_N) on output text files. You must test the parameterized CORDIC circuit for N = 12 and N = 16. The testbench must:
 - ✓ Read input values (x_0, y_0, z_0) from two input text files (provided):
 - in_benchR.txt: Data for Rotation Mode testing. 100 data points (x_0, y_0, z_0) . Data format: [16 14]. Each line per data point written as hexadecimals: $|x_0|y_0|z_0|$. Data set: $x_0 = 0, y_0 = 1/A_n, z_0 = -\pi/2$ to $\pi/2$. z_0 : 100 equally-spaced values between $-\pi/2$ to $\pi/2$. With this data set in the rotation mode, note that $x_N \to -\sin(z_0), y_N \to \cos(z_0)$.
 - in_benchV.txt: Data for Vectoring Mode testing. 100 data points (x_0, y_0, z_0) . Data format: [16 14]. Each line per data point written as hexadecimals: $|x_0|y_0|z_0|$. Data set: $x_0 = 0.0$ to $0.5, y_0 = 1, z_0 = 0$. x_0 : 100 equally-spaced values between 0.0 to 0.5. With this data set in the vectoring mode, note that $x_N \to A_n \sqrt{x_0^2 + y_0^2}, z_N \to atan(y_0/x_0)$.
 - ✓ Write output results (x_N, y_N, z_N) on out_bench_N12.txt and out_bench_N16.txt. Data format: [16 14], each line per data point written as hexadecimals: $|x_N|y_N|z_N|$. Each output text file should have 200 data points (100 from the rotation mode and 100 from the vectoring mode). Using a handful of data points, verify that your results are correct.
- Your testbench must fed data at the rate of one set per cycle (as this is a pipelined circuit). See figure below for reference. Output data should appear at the same rate (after N+1 cycles since the first data was entered).



- Tips:
 - ✓ Vivado: Make sure that the input text files are loaded as simulation sources.
 - ✓ Vivado: The output text file should appear in sim/sim 1/behav.
 - ✓ Vivado: To represent data as fixed-point numbers, use Radix → Real Settings in the Vivado simulator window.
 - ✓ For reference, the following MATLAB script can be useful: cordic_example_ece4710.m. It generates the input text files and reads the output textfile (out_bench.txt) as specified here. It uses the Circular CORDIC MATLAB/Octave model.

OPTIONAL SECOND ACTIVITY: PROCESS DATA READ FROM OUTPUT TEXT FILES (+10)

- Read data from output text files in MATLAB® (or Octave). Convert data to their corresponding real numbers.
- Plot the results (rotation and vectoring modes for N=12,16) along with the function values (Rotation: $x_N \to -sin(z_0)$, $y_N \to cos(z_0)$. Vectoring: $x_N \to A_n \sqrt{x_0^2 + y_0^2}$, $z_N \to atan(y_0/x_0)$ to which the CORDIC results should converge. The values will be very close, so plot graphs individually. atan in the CORDIC algorithm has a different definition, called atan2.



Instructor: Daniel Llamocca TAs: David Stern, Luke Nuculaj • Compute the MSE for each case. This metric assesses how close the hardware results are to the ideal ones (function values to which the CORDIC results converge). The smaller the MSE, the more accurate the hardware results are.

	Rota	Rotation		Vectoring	
	N=12	N=16	N=12	N=16	
x_N					
y_N					
Z_N					

$$MSE = \frac{1}{T} \sum_{i=1}^{T} (D_i - \widehat{D}_i)^2$$

Demonstrate this to your TA. ______ (TA signature/date)

SUBMISSION

- Submit to Moodle (an assignment will be created):
- ✓ This lab sheet (as a .pdf) completed (if applicable) and signed off by the TA (or instructor).
 - Note: The lab assignment has two activities. You get full points of the 1st activity if you demo it by the due date. You can demo the 2nd activity by the due date or late (here, we apply a penalty towards the points of the 2nd activity).
 - √ (As a .zip file) All the generated files: VHDL code, VHDL testbench, and XDC file. DO NOT submit the whole Vivado Project.
 - Your .zip file should only include one folder. Do not include subdirectories.
 - It is strongly recommended that all your design files, testbench, and constraints file be located in a single directory.
 This will allow for a smooth experience with Vivado.
 - You should only submit your source files AFTER you have demoed your work. Submission of work files without demoing will be assigned <u>NO CREDIT</u>.

TA signature:	Date:
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